



### Bayesian optimization applications at the **Argonne Wakefield Accelerator Facility**

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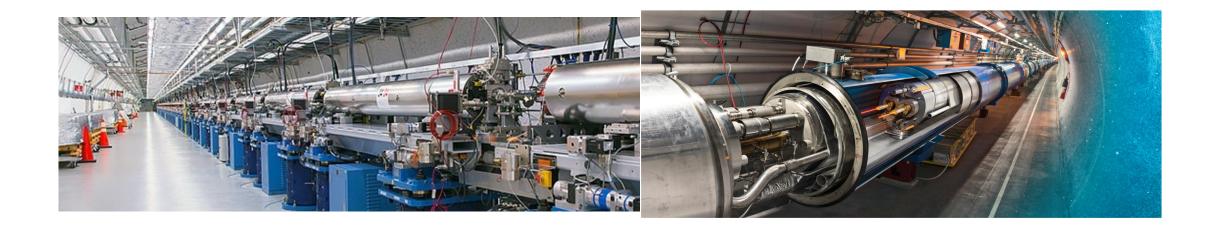




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- Must meet various beam quality objectives
- Have many components and constraints
- Observations are limited

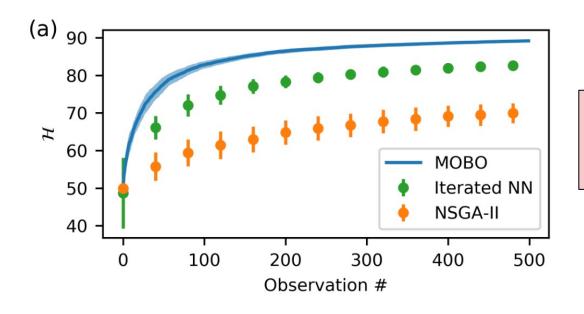
https://lcls.slac.stanford.edu/overview

https://home.cern/sites/home.web.cern.ch/files/2018-07/factsandfigures-en\_0.pdf





- Current methods require multiple observations / parallel computing
- Converge to Pareto front slowly when serialized (thousands of observations)
- Not ideal for online tuning



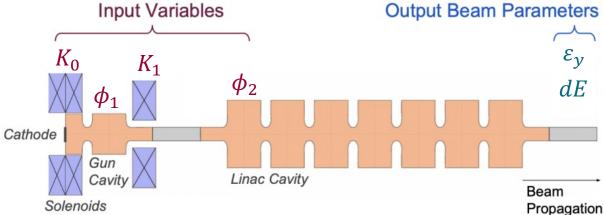
Multi-Objective Bayesian Optimization: Reduces observations needed to converge by at least one order of magnitude



#### Experiment at AWA photoinjector







• Input variables:  $\{K_0, K_1, \phi_1, \phi_2\}$ 

• Minimize objectives:  $\{\varepsilon_y, dE\}$ 

(Simultaneously and with few observations)

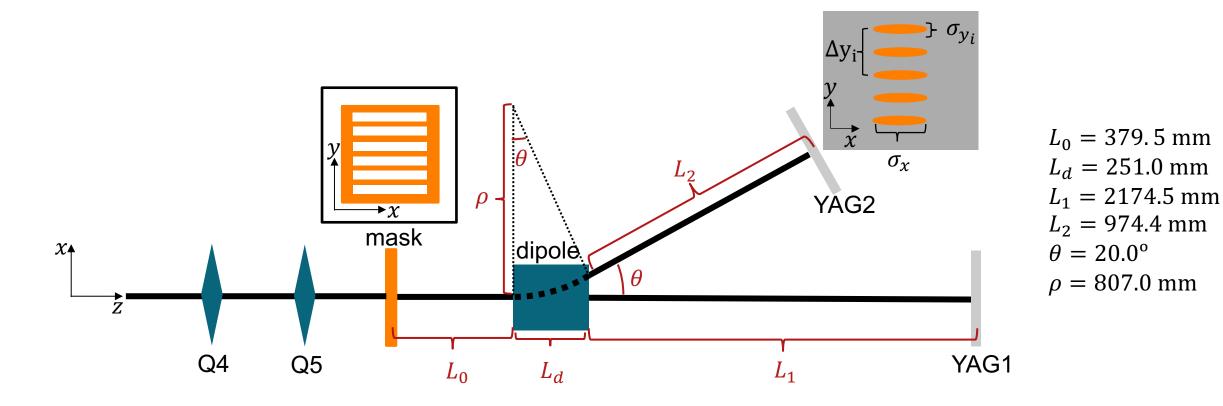
Q = 5 nC  $\sigma_t = 6 \text{ ps}$  $\langle E \rangle = 42 \text{ MeV}$ 

Adapted from: https://doi.org/10.1103/PhysRevAccelBeams.23.044601





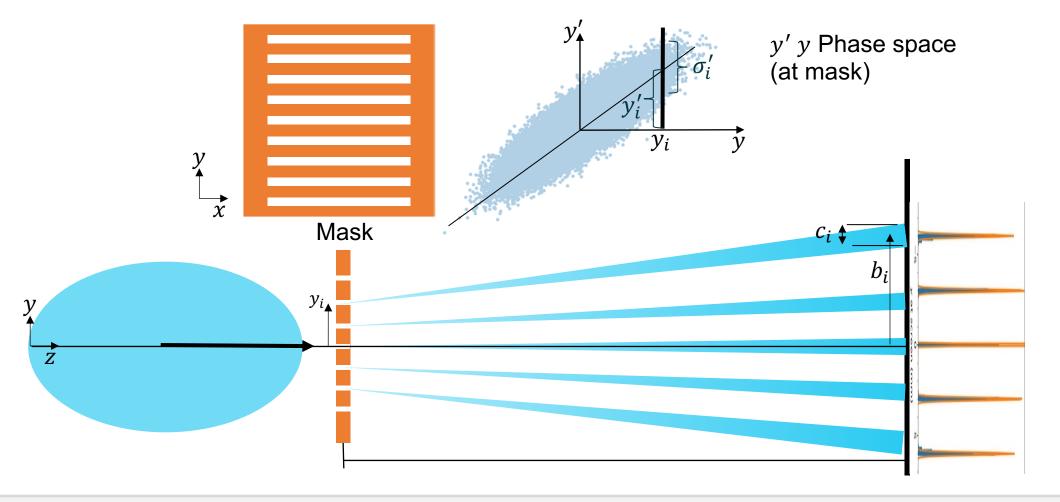








- Beamlets' intensities, location and width at YAG determine emittance at mask
- Explore parameters: solenoids (+ quads)





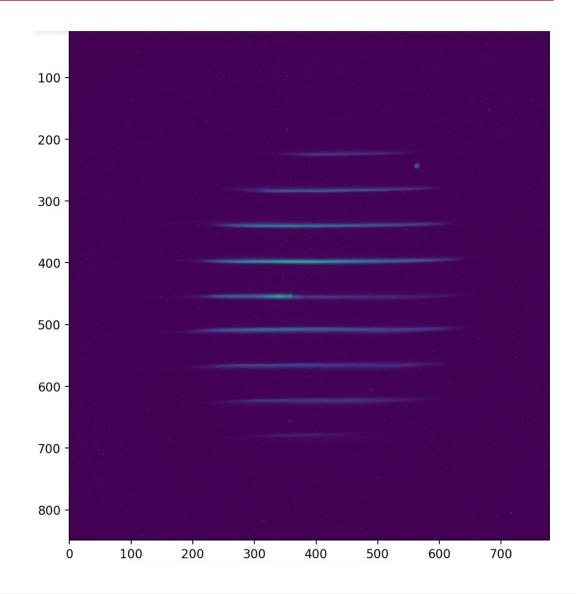


#### $\varepsilon_y$ measurement is valid if:

- Number of blobs > 3
- Blobs don't touch
- No blobs outside the screen

#### $\varepsilon_y$ is difficult to explore and characterize:

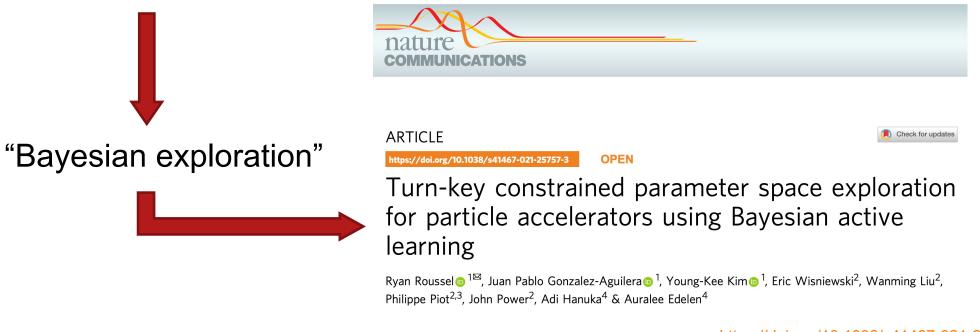
- $\varepsilon_y$  and validity depend on input variables
- No prior knowledge of where is the valid region in input space





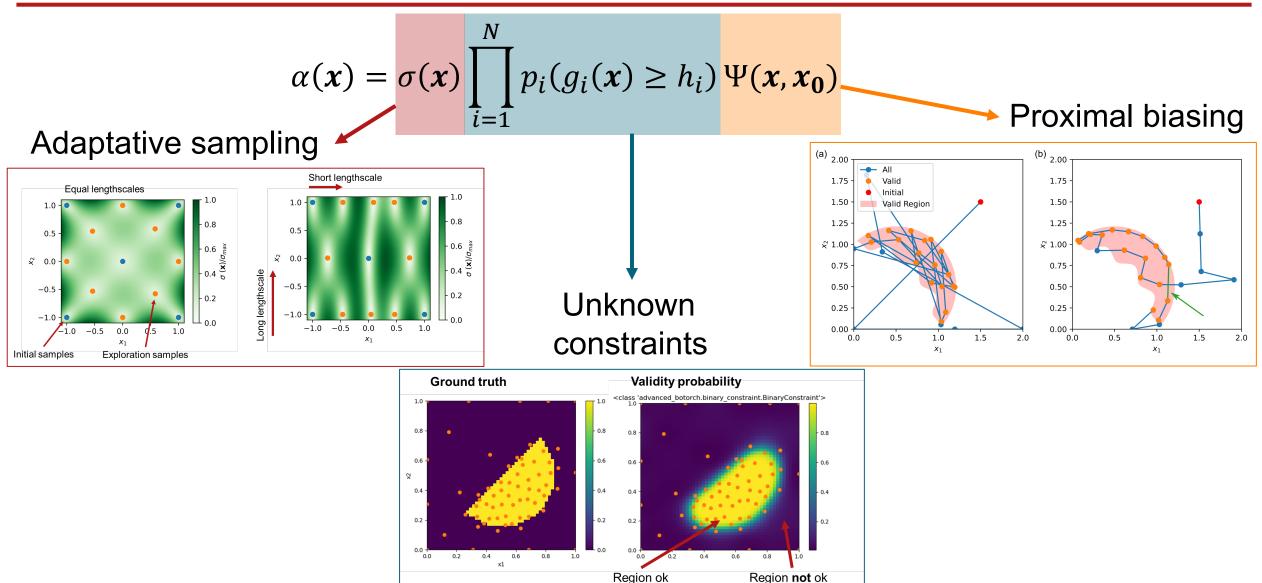


- Exploring input space is difficult
  - -Emittance measurement is highly constrained
  - -Limited prior knowledge on the beam response/measurement validity with respect to inputs
  - -Result: Grid scans are inefficient
- What if we adapt Bayesian optimization to maximize information gain?



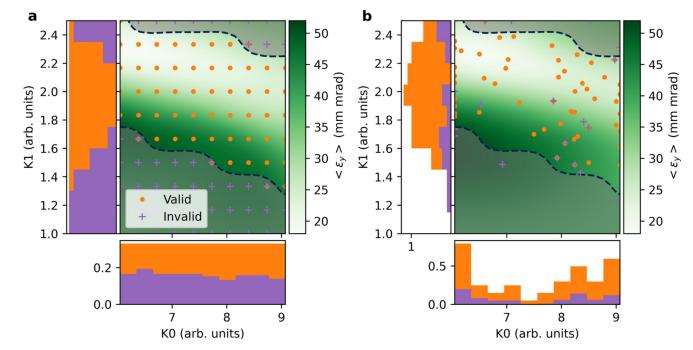
## **Constrained Proximal Bayesian Exploration**



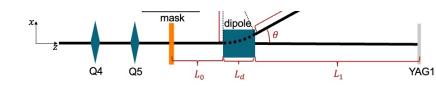




#### **Characterizing Emittance at AWA**



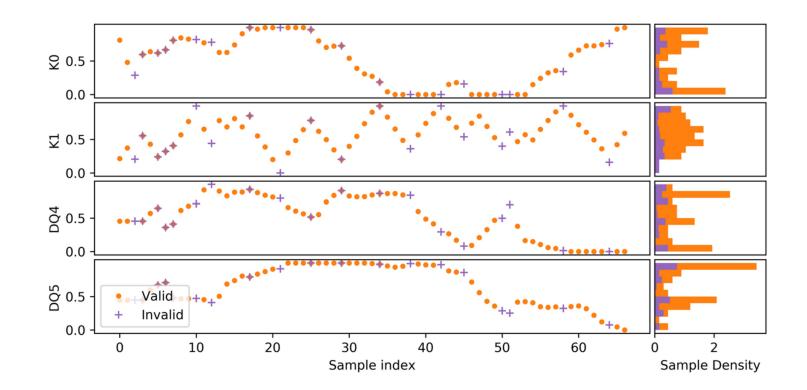
- Avoids invalid regions (77% vs 52% validity)
- Samples valid region with shorter length scales over  $K_1$ (identifies that  $\varepsilon_y$  varies faster along  $K_1$ )
- Improves characterization of functional dependence
- Allows exploration of 4D input space (solenoids + quads)



https://doi.org/10.1038/s41467-021-25757-3



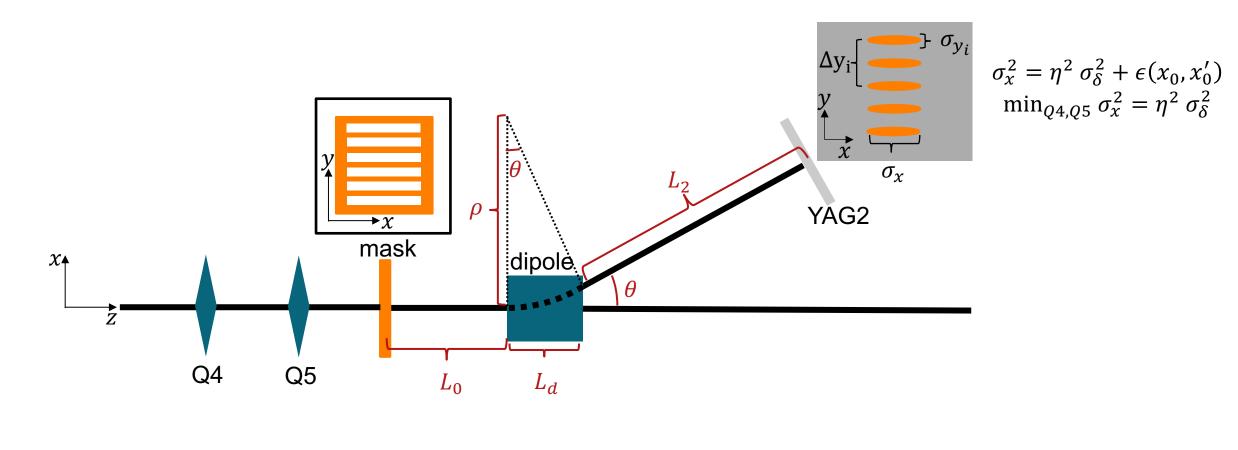




- Scans  $K_1$  back and forth across valid input region
- Reduces redundant measurements on other inputs with longer length scales







• Must minimize  $\sigma_x$  for each measurement Quality-aware B.O.





# Questions?





# Autodifferentiable accelerator modeling (Project just started)

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• Computers execute sequence of elementary operations/functions

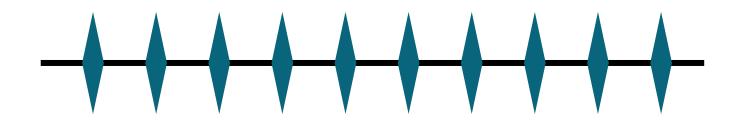
(+, -, ×, ÷, e, log, sin, cos, ...)

- Computer functions are composed of these sequences
- Autodiff uses the derivatives of these elementary operations/functions and the chain rule to evaluate the derivative of a computer function
- This results in fast and accurate derivatives





Toy-model: lattice composed of 10 quads separated by drifts.



- Want to optimize some beam property downstream (e.g.,  $\sigma_x$ )
- but... high-dimensional input space
- We can test gradient-based optimization methods providing gradient information using autodiff





# Thanks!